

X SERIES

# Servo Drives

May 2009



#### **Bus Voltage Input**

- 20 100 VDC
- 100 365 VDC

#### **Control Modes**

- Gearing
- Position
- Velocity
- Torque

#### **Command Interface**

- Step/Direction
- ± 10V Velocity or Torque Command
- Master encoder (gearing)
- Network (EtherCAT, CANopen)
- Descrete I/O

#### Communication

- USB
- Network

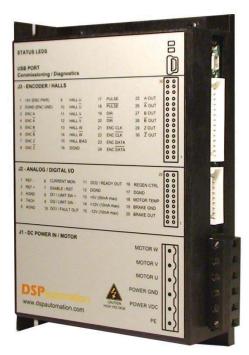
#### Servomotor Feedback

- Incremental quadrature A/B encoder
- Resolver
- Serial Encoder (BiSS, EnDAT 2.2)
- Digital Halls

The X Series servo drive is for powering brushless or brush servomotors. The VDC input bus allows for lower cost multi-axis solutions and space saving. Logic control power is internally generated from the dc bus. An option is available for 24 VDC isolated control power supplied externally by the end user. The small package design outputs up to 3.6 kW continuous power.

The X Series all digital servo drive utilizes a 32 bit digital signal processor (DSP) and 16 bit A/D's and D/A's for control loops and servomotor feedback inputs to provide ultimate high performance. The drive controls the failsafe brake and thermal sensing from the servomotor. Servomotor feedback is a determining factor in performance of a servo system. The X Series comes standard with BiSS and EnDAT 2.2 serial encoder or SSI interface.

The X Series supports EtherCAT, <u>www.ethercat.org</u> and CANopen, <u>www.canopen.org</u>. Other networks are available on request.



#### Setup and Commissioning

A USB port on the servo drive is used for communication between the servo drive and PC (personal computer). DSP Automation provides easy to us Window ™ software for setup and commission.

Setup requires setting the parameters for the *servo drive* and the *servomotor*. These parameters are easily set by the user or DSP Automation will preset for the customer if requested.

Commissioning the system for optimum performance is a challenge for most users. DSP Automation provides standard and advanced control adjustments for the optimum performance required for the application. An integrated two channel oscilloscope provides instantaneous feedback for visually viewing the dynamic performance of the system.

DSP Automation does not leave the task of commissioning the servo system to the experience of our customers. We provide full support to guarantee success. To qualified customers, a DSP Automation engineer will be at the customer's location for commissioning and training for the first system.

### Technical Specifications X Series (VDC)

Input Voltage			20 - 10	0 VDC <b>or</b> 10	0 - 365 VDC			
Output Current	Continuous current @ 40° C (A rms)	1	2	4	6	8	12	15
	Peak (A rms)	3	6	12	18	24	30	30
	Peak Current Time (sec.)				3			

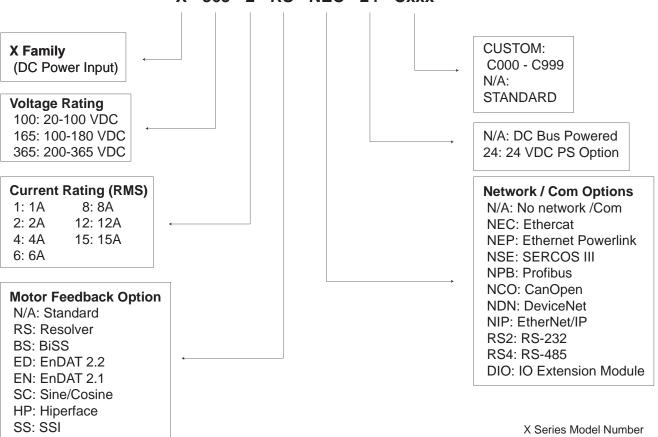
## **Performance Specifications**

Control Logic Voltage	Internal DC/DC converter					
Current Loop BW	3.0kHz					
Velocity Loop BW	600Hz					
PWM Frequency	20kHz					
Emulated Encoder Max Output Frequency	2.5 MHz					
Commissioning/ Diagnostics	Software (USB port), LEDs					
Encoder Feedback	Incremental Encoder / Halls Absolute Serial: Single / Multiturn, 17-25bit, BiSS / EnDAT 2.2 / SSI Tachometer: (+/-50V max.) 16-bit A/D Resolution					
Operating Modes	Torque, Velocity, Pulse & Direction, Encoder Follower, Sensorless (Brushed only)					
Motor Temperature Sensor	NTC, PTC, Thermostat					
Motor Current Waveform	Sinusoidal					
Analog Input	+/-10V, 16-bit A/D Resolution, software scalable					
Analog Output	+/-10V, Software Selectable/scalable					
Digital Inputs	3 Inputs, 5-28VDC control voltage					
Digital Outputs	2 Software Selectable Outputs, 5-28VDC, 100mA max.					
Servomotor Brake Software Selectable Output, 24-28VDC, 3A max.   Control (user supplied power)						
Operating Ambient Temperature	0 °C to 50 °C					
Relative Humidity	5 - 95% non-condensing					
Regen Capability	Internal Resistor 30W cont., 1kW peak External Resistor Up to 100% of Drive Capacity					

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## SERVO DRIVE MODEL NUMBER



X - 365 - 2 - RS - NEC - 24 - Cxxx

Examples:

- + 45 VDC bus, 8 amps continuous with standard incremental encoder input  $\_$  X-100-8
- 300 VDC bus, 4 amps continuous with standard incremental encoder input \_ X-365-4
- 160 VDC bus, 6 amps continuous with resolver \_ X-365-6-RS
- 300 VDC bus, 2 amps continuous with BiSS serial encoder and CANopen network \_ X-365-2-BS-NCO

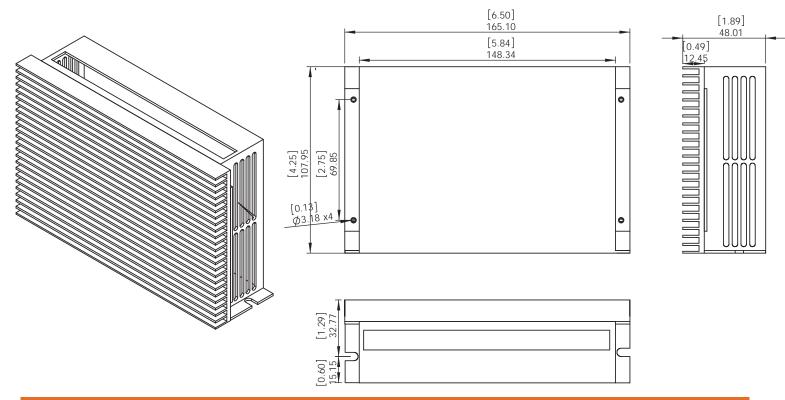
ZROHS/CE

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ommissioning / D			30	
- ENCODER / HA	ALLS		50	000
+5V (ENC PWR)	9 HALL U	17 PULSE	25 A OUT	00
DGND (ENC GND)	10 HALL U	18 PULSE	26 A OUT	000
ENC A	11 HALL V	19 DIR	27 BOUT	00
ENCA	12 HALL V	20 DIR	28 BOUT	000
ENC B	13 HALL W	21 ENC CLK	29 Z OUT	00
ENC B	14 HALL W	22 ENC CLK	30 Z OUT	000
ENC Z	15 HALL BIAS	23 ENC DATA		00
ENCZ	16 DGND	24 ENC DATA		00
				001
REF + 7 ENA AGND 8 DI1 TACH 9 DI2	ABLE / RST 12 / LIMIT SW + 13 / LIMIT SW - 14	DGND +5V (50mA max) +12V (10mA max)	16 REGEN CTRL 17 DGND 18 MOTOR TEMP 19 BRAKE GND 20 BRAKE OUT	0000000
1 - DC POWER IN	I / MOTOR		MOTOR W	1.
			MOTOR V	•>
			MOTOR U	•>
		A	POWER GND	•>
<b>DSP</b> aul		CAUTION HIGH VOLTAGE	POWER VDC	• >
www.dspautor	mation com		PE	

X SERIES (8-15 amps cont.) [6.50] 165.10 MOUNTING DRAWING, UNITS: MM (INCH) [2.43] 61.60 [5.84] 148.34 **(** e • T [4.25] 107.95 [2.75] 69.85 [0.13] Ø3.18 x4 0 [1.83] 46.36 [0.60] 15.15

X SERIES (1-6 amps cont.) MOUNTING DRAWING, UNITS: MM (INCH)



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DSP Automation, Inc.